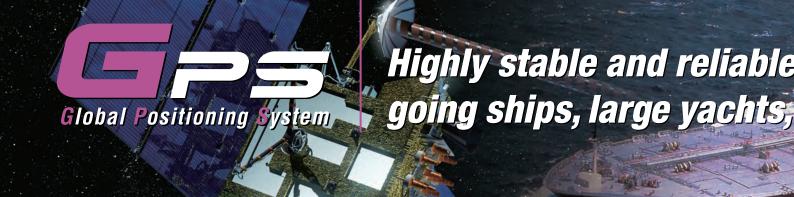
# FURUNO







- Ideal position sensor for Radar, AIS, ECDIS, autopilot, echo sounder and other navigation and communications equipment
- ► Full compliance with IMO MSC. 112 (73) and IEC 61108-1: performance and testing standards for GPS receiver
- Newly designed GPS chip and antenna unit deliver enhanced stability and precision in position fixing
  Enhanced noise rejection capabilities are incorporated in the GPS receiver chip, delivering

Enhanced noise rejection capabilities are incorporated in the GPS receiver chip, delivering anti-jamming function as well as high level of tolerance towards multi-path mitigation. Also, the tolerance towards multi-path mitigation is enhanced when GPA-020S or GPA-021S antenna unit is used.

- ► Augmentation to enhance precision by utilizing SBAS (Satellite-Based Augmentation System) and DGPS (an optional DGPS radio beacon receiver as well as GPA-021S antenna unit required)
- ► Fully complies with IMO MSC. 114 (73) and IEC 61108-4: performance and testing standards for DGPS radio beacon receiver
- ▶ 10 Hz position update rate (position updated every 0.1 second) making steady own ship position tracking possible
- ► USB port available on the front panel

  Routing data, menu setting, user setting can be exported/imported through USB jump drives
- Variety of display modes available:
  Plotter, Course, Highway, Data and Integrity
  - A Basic positioning data such as own ship position data, its data integrity, time, etc., are presented. Also, display mode as well as notice icons are displayed.
  - The area shows the information specific to the display mode currently selected. Please refer to each of the display modes for details.
  - © Guide to currently available actions is displayed. Under alert situation, the information about the most imminent alert is displayed.

# Dual configuration for back-up purpose to ensure system availability

Information about waypoints, route and other data set by the operators on the one unit can be shared with the other unit for functional back-up

# ► BAM (Bridge Alert Management) ready

Meets the specific requirements for alerts and interconnection with Bridge Alert Management in IMO MSC.302 (87)

# LAN interface available for efficient network integration into a bridge system

The GP-170 is fully Light Weight Ethernet (IEC 61162-450) compatible

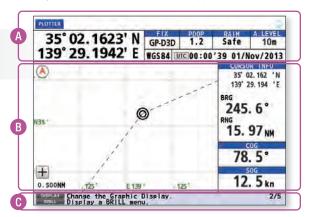
# ► 5.7" color LCD (with 640 x 480 pixels) for data presentation

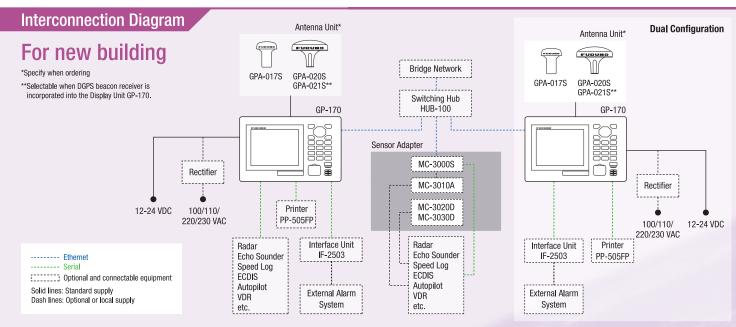
# ► Simplified menu operation

The operator can navigate through the menu tree either by pressing the cursor pad or pressing the corresponding numbers on the numeric keypad to the menu items

# ► Enhanced route planning/management function available

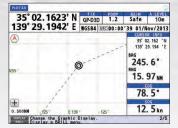
- Comprehensive range of voyage information to be incorporated in routes
- Streamlined route creation through combination with an external PC
- Sharing the active route information with ECDIS to supplement the ECDIS route monitoring capability





# position fixing system for ocean ferries and commercial vessels

# **Plotter**



# Information to be displayed:

- ► Simplified plotter display
- ► Cursor information
- ► Contextual menu
- ► SOG/COG data boxes

# Integrity



# Information to be displayed:

- Skyplot presentation of currently viewable satellites
- Status on GNSS/SBAS satellite signal reception; incl. signal strength/signal to noise ratio (in bar/line charts)
- ► Elevation angles of the available satellites
- ▶ Detailed information about the beacon stations

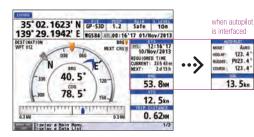
# **Highway**



# Information to be displayed:

- ► Course information
- ► SOG/COG data boxes
- ► User-preset cross track limit of deviation (XTE)
- ► Own ship gauge, showing the attitude of the ship, incl. pitch, roll and heave

# Course



# Information to be displayed:

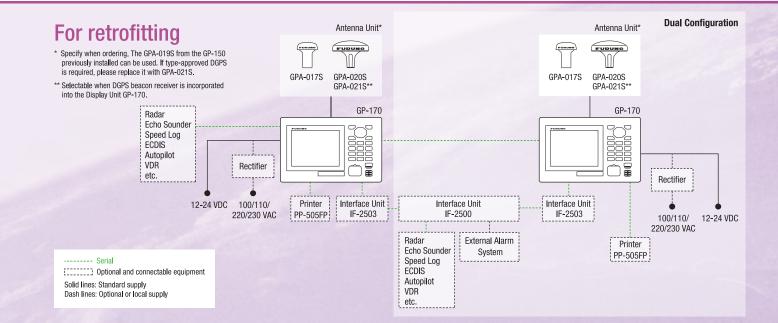
- ► Graphical presentation of course information, incl. current waypoint, bearing to the destination, COG, XTE
- Estimated Time of Arrival data box, incl. required time to reach the current/next waypoints and range to the waypoint\* \*when autopilot is interfaced, the following information is shown in the data boxes Autopilot status data box, incl. mode, ship's heading, rudder angle, and COG, and SOG data box.
- ► Velocity to destination
- ► Trip distance data

# Data.



# Information to be displayed:

► Navigation data boxes configurable according to the needs of the operators



# **SPECIFICATIONS**

Product Name		
GPS NAVIGATOR		
Receiver		
Number of channels	GPS	12 ch
	SBAS	2 ch
RX frequency	GPS	1575.42 MHz±1.023 MHz
Tracking code	GPS	C/A
	SBAS	C/A
Accuracy*	GPS	not exceeding 10 m (2 drms, HDOP<4)
	DGPS	not exceeding 5 m (2 drms, HDOP<4)
	WAAS	not exceeding 3 m (2 drms, HDOP<4)
	MSAS	not exceeding 7 m (2 drms, HDOP<4)
	QZSS (SLAS) L1S	not exceeding 3 m (2 drms, HDOP<4)
Tracking velocity		1,000 kn
Position fixing time		90 sec when cold start
Position update rate		every 1 sec (standard); every 0.1 sec (max.)
Beacon receiver	Frequency range	283.5 to 325.0 kHz
(optional internal kit) MSK rate		25, 50, 100, 150, 200 bps

<sup>\*</sup> Dependent on ionospheric activity and multipath

# **Display Unit**

	5.7" color LCD (116.16 mm x 87.12 mm)	
	640 (H) x 480 (V) pixels (VGA)	
	700 cd/m <sup>2</sup>	
	Plotter, Highway, Course, Data, Integrity	
Projection	Mercator	
Memory capacity	1,000 points for ship's track with comments	
	up to 20 characters; 2,000 points for waypoints;	
	100 routes (containing up to 1,000 waypoints per 1 route)	
	GNSS, Graph, Beacon	
	Differential positioning interruption, HDOP	
	overshoot, own ship positioning fail, own	
	ship position lost, BEACON signal lost,	
	BEACON malfunction, antenna short-circuit	
	Arrival and anchor watch, XTE, Speed, Trip	
	Safe, Unsafe, Caution	

### Interface

Ports		Serial ports: 2 ports (In/Out), 1 port (Out) IEC 61162-1, 1 port (In/Out)		
		IEC 61162-2; Ethernet: 1 port IEC 61162-450; USB: 1 port (front panel)		
Output	Serial	AAM, ALC, ALF, ALR, APA, APB, ARC, BOD, BWC, BWR, BWW,		
		DTM, GBS, GGA, GLL, GNS, GRS, GSA, GST, GSV, HBT, MSK*		
		MSS**, POS, RMB, RMC, Rnn, RTE, VDR, VTG, WCV, WNC,		
		WNR, WPL, XTE, ZDA, RTCM sc104		
		*when either internal/external beacon receiver is used		
		** when internal beacon receiver is used		
	Ethernet	AAM, ALC, ALF, ALR, APB, ARC, BOD, BWC, BWR, BWW, DTM,		
		GBS, GGA, GLL, GNS, GRS, GSA, GST, GSV, HBT, POS, RMB,		
		RMC, RTE, VDR, VTG, WCV, WNC, WPL, XTE, ZDA		
Input Seri	Serial	ACK, ACN, CRQ, DBT, DPT, HBT, HDG, HDM, HDT, MSK, MSS,		
		MTW, THS, TLL, VBW, VHW		
	Ethernet	ACK, ACN, DBT, DPT, HBT, HDG, HDM, HDT, MTW, THS, TLL,		
		VBW, VHW		

# **ENVIRONMENT**

Temperature	Display Unit:	-15°C to +55°C
	Antenna Unit:	-25°C to +70°C
Relative humidity		95% or less at 40°C
Degree of protection	Display Unit:	IP25
	Antenna Unit:	IP56

### **POWER SUPPLY**

12-24 VDC

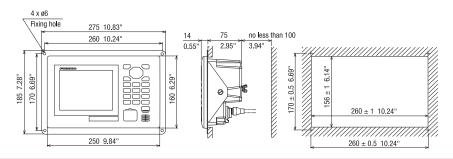
# **EQUIPMENT LIST**

Standard	1. Display Unit	GP-170	1 unit		
	2. Antenna Unit	GPA-017S	1 unit		
		GPA-020S	1 unit		
		GPA-021S*	1 unit		
			(specify when ordering)		
			* Selectable when a beacon receiver is incorporated into a display unit.		
	3. Antenna Cables	S Selectable from 15 m/30 m/40 m/50 m			
	4. Installation Materials and Spare Parts				
Option	1. DGPS Receiver Kit	OP20-42			
	2. Antenna Cable	15 m/30 m/4	40 m/50 m		
	3. Network Cable	3 m with wat	terproof connector MOD-WPAS0001-030+		
	4. Flush Mount Kit	OP20-40/41			
	5. Antenna Base	NO. 13-QA3	30/NO. 13 QA310/NO. 13-RC5160		
	6. Interface Unit	IF-2503			
	7. Rectifier	PR-62, PR-2	240		

# **Display Unit**

# GP-170 (with an optional flush mount kit)

2.2 kg 4.9 lb (without DGPS beacon receiver) 2.4 kg 5.3 lb (with DGPS beacon receiver)

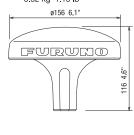


# **Antenna Unit**

GPA-017S (for GPS)

0.12 kg 0.26 lb

632 1.3" 632 1.3" **GPA-020S** (for GPS) 0.32 kg 0.71 lb **GPA-021S** (for DGPS) 0.52 kg 1.15 lb



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